

Five-Dimensional Tangent Vectors in Space-Time

V. Generalization of Covariant Derivative

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Abstract

In this part of the series I discuss the five-vector generalizations of affine connection and gauge fields. I also give definition to the exterior derivative of nonscalar-valued five-vector forms and consider the five-vector analogs of the field strength tensor. In conclusion I discuss the nonspacetime analogs of five-vectors.

A. Five-vector affine connection

As is known, the notion of the gradient for four-vector fields cannot be formulated invariantly without introducing an additional structure on the space-time manifold, which is called the affine connection. Formally, the latter can be viewed as a map

$$\nabla : \mathcal{D} \times \mathcal{D} \rightarrow \mathcal{D}, \quad (1)$$

where \mathcal{D} is the set of all four-vector fields (derivations). The image of a pair of fields (\mathbf{U}, \mathbf{V}) is denoted as $\nabla_{\mathbf{U}}\mathbf{V}$ and is called the covariant derivative of field \mathbf{V} in the direction of field \mathbf{U} . By definition, ∇ satisfies the following three requirements:

$$\nabla_{(f\mathbf{U}+g\mathbf{V})}\mathbf{W} = f \cdot \nabla_{\mathbf{U}}\mathbf{W} + g \cdot \nabla_{\mathbf{V}}\mathbf{W}, \quad (2a)$$

$$\nabla_{\mathbf{U}}(\mathbf{V} + \mathbf{W}) = \nabla_{\mathbf{U}}\mathbf{V} + \nabla_{\mathbf{U}}\mathbf{W}, \quad (2b)$$

$$\nabla_{\mathbf{U}}(f\mathbf{V}) = \partial_{\mathbf{U}}f \cdot \mathbf{V} + f \cdot \nabla_{\mathbf{U}}\mathbf{V} \quad (2c)$$

for any scalar functions f and g and any four-vector fields \mathbf{U}, \mathbf{V} , and \mathbf{W} . There exists a regular way in which the notion of the covariant derivative can be extended to the fields of all other four-tensors. One first defines it for an arbitrary 1-form field $\tilde{\mathbf{S}}$: $\nabla_{\mathbf{U}}\tilde{\mathbf{S}}$ is such that

$$\langle \nabla_{\mathbf{U}}\tilde{\mathbf{S}}, \mathbf{V} \rangle = \partial_{\mathbf{U}}\langle \tilde{\mathbf{S}}, \mathbf{V} \rangle - \langle \tilde{\mathbf{S}}, \nabla_{\mathbf{U}}\mathbf{V} \rangle \quad (3)$$

for any four-vector field \mathbf{V} . The covariant derivatives of all other four-tensor fields can then be defined by induction according to the formula

$$\nabla_{\mathbf{U}}(\mathbf{M} \otimes \mathbf{N}) = \nabla_{\mathbf{U}}\mathbf{M} \otimes \mathbf{N} + \mathbf{M} \otimes \nabla_{\mathbf{U}}\mathbf{N}, \quad (4)$$

where \mathbf{M} and \mathbf{N} are any two four-tensor fields. For an arbitrary scalar function f one takes that

$$\nabla_{\mathbf{U}}f \equiv \mathbf{U}f = \partial_{\mathbf{U}}f. \quad (5)$$

The meaning of all these formal definitions becomes apparent if one interprets the value of $\nabla_{\mathbf{U}}\mathbf{V}$ at each space-time point as a derivative of field \mathbf{V} along a parametrized curve whose tangent four-vector is \mathbf{U} , calculated by using certain rules of parallel transport. At an arbitrary point P , this latter derivative is constructed by the following obvious procedure: (i) Take \mathbf{V} at $\lambda = \lambda(P) + \Delta\lambda$. (ii) Parallel transport it back to P . (iii) Calculate how much it differs from \mathbf{V} there. (iv) Divide by $\Delta\lambda$ and take the limit $\Delta\lambda \rightarrow 0$. Any derivative calculated this way satisfies requirement (2c) and is such that

$$\nabla_{(f\mathbf{U})}\mathbf{V} = f \cdot \nabla_{\mathbf{U}}\mathbf{V} \quad (6)$$

for any f, \mathbf{U} , and \mathbf{V} , which is nothing but requirement (2a) at $g = 0$. To satisfy requirement (2a) completely, ∇ should also have the property

$$\nabla_{(\mathbf{U}+\mathbf{V})}\mathbf{W} = \nabla_{\mathbf{U}}\mathbf{W} + \nabla_{\mathbf{V}}\mathbf{W} \quad (7)$$

for any \mathbf{U}, \mathbf{V} , and \mathbf{W} , which can be interpreted in the following way: the parallel transport of four-vectors along any finite continuous curve within any given region of space-time is completely determined by the rules of parallel transport along the coordinate lines of an arbitrary coordinate system (or systems) that covers the above region completely. Requirement (2b) is equivalent to saying that parallel transport is a linear operation. Equation (3) means that parallel transport conserves the contraction of a four-vector and a four-vector 1-form. Equation (4) means that the rules of parallel transport for different four-tensors are correlated with one another in such a way that the tensor product of any two four-tensors \mathbf{M} and \mathbf{N} is transported into the tensor product of the transported \mathbf{M} and transported \mathbf{N} . Equation (5) also becomes obvious.

In part I the covariant derivative has been introduced for five-vector fields. This is equivalent to introducing a map

$$\nabla : \mathcal{D} \times \mathcal{F} \rightarrow \mathcal{F}. \quad (8)$$

Considering the way five-vectors are related to four-vectors, one can regard the structure defined on space-time by this map as an extension of the structure defined on it by map (1). The subsequent replacement of $\nabla_{\mathbf{U}}$ with the operator $\nabla_{\mathbf{u}} = \nabla_{(\mathbf{u}^z)}$ is equivalent to replacing map (8) with a map

$$\nabla : \mathcal{F}_{\mathcal{Z}} \times \mathcal{F} \rightarrow \mathcal{F}, \quad (9)$$

which is more a formality, since \mathcal{D} is isomorphic to $\mathcal{F}_{\mathcal{Z}}$. It now seems natural to make one more step in generalizing the concept of affine connection to five-vectors and consider a map

$$\square : \mathcal{F} \times \mathcal{F} \rightarrow \mathcal{F}, \quad (10)$$

which will be called the *five-vector affine connection*. The image of a pair of fields (\mathbf{u}, \mathbf{v}) with respect to \square will be denoted as $\square_{\mathbf{u}}\mathbf{v}$ and will be called the *five-vector covariant derivative* of field \mathbf{v} in the direction of field \mathbf{u} . To give \square a formal definition, one should formulate certain requirements, similar to requirements (2) for ∇ , which should be satisfied by \square . The analogs of equations (2a) and (2b) are quite obvious:

$$\square_{(f\mathbf{u}+g\mathbf{v})}\mathbf{w} = f \cdot \square_{\mathbf{u}}\mathbf{w} + g \cdot \square_{\mathbf{v}}\mathbf{w}, \quad (11a)$$

$$\square_{\mathbf{u}}(\mathbf{v} + \mathbf{w}) = \square_{\mathbf{u}}\mathbf{v} + \square_{\mathbf{u}}\mathbf{w}, \quad (11b)$$

for any scalar functions f and g and any five-vector fields \mathbf{u} , \mathbf{v} , and \mathbf{w} . To make a rational choice of the analog of requirement (2c), let us first formulate explicitly the condition that the structure defined on space-time by \square is an extension of the structure defined on it by ∇ . The latter statement apparently means that the restriction of \square to $\mathcal{F}_{\mathcal{Z}} \times \mathcal{F}$ should coincide with map (9), which in its turn means that

$$\square_{(\mathbf{u}^z)} = \nabla_{\mathbf{u}} \quad (12)$$

for any five-vector field \mathbf{u} . Together with requirement (11a), the latter equation yields

$$\square_{\mathbf{u}} = \nabla_{\mathbf{u}} + \varsigma \lambda_{\mathbf{u}} \square_{\mathbf{1}}. \quad (13)$$

Since the five-vectors from \mathcal{E} do not correspond to any direction in space-time, let us assume that $\square_{\mathbf{1}}$ is a *purely algebraic* operator, so

$$\square_{\mathbf{1}}(f\mathbf{v}) = f \cdot \square_{\mathbf{1}}\mathbf{v} \quad (14)$$

for any five-vector field \mathbf{v} and any scalar function f . From the latter equation and formula (13) one obtains the relation

$$\square_{\mathbf{u}}(f\mathbf{v}) = \partial_{\mathbf{u}}f \cdot \mathbf{v} + f \cdot \square_{\mathbf{u}}\mathbf{v}, \quad (11c)$$

which is the desired analog of requirement (2c) for \square .

Let us now define the action of \square on scalar functions. Considering what has been said above, it seems reasonable to think that the action of $\square_{\mathbf{u}}$ on an arbitrary scalar function f should produce a sum of the derivative $\partial_{\mathbf{u}}f$ and a term of the form $a\lambda_{\mathbf{u}}f$, where a is a constant. One should now notice that if one adds to \square a term proportional to $\lambda_{\mathbf{u}}\mathbf{1}$, one will obtain an operator that will still satisfy requirements (11), but whose action on scalar functions will be different. In particular, one can select this additional term in such a way that the action of the resulting operator on f would yield $\partial_{\mathbf{u}}f$. In the following, the notation $\square_{\mathbf{u}}$ will refer to this particular choice of the five-vector covariant derivative operator, and so

$$\square_{\mathbf{u}}f = \partial_{\mathbf{u}}f. \quad (15)$$

As it follows from equations (11c) and (15), the action of \square on the product of two scalar functions and on the product of a scalar function and a five-vector field obeys the Leibniz rule. Let us assume that the same rule holds for the contraction and tensor product. This will enable us to define the action of \square on an arbitrary five-vector 1-form field $\tilde{\mathbf{s}}$ according to the formula:

$$\langle \square_{\mathbf{u}}\tilde{\mathbf{s}}, \mathbf{v} \rangle = \partial_{\mathbf{u}}\langle \tilde{\mathbf{s}}, \mathbf{v} \rangle - \langle \tilde{\mathbf{s}}, \square_{\mathbf{u}}\mathbf{v} \rangle \quad (16)$$

for any five-vector field \mathbf{v} , and, by induction, on the fields of all other five-tensors according to the formula

$$\square_{\mathbf{u}}(\mathbf{m} \otimes \mathbf{n}) = \square_{\mathbf{u}}\mathbf{m} \otimes \mathbf{n} + \mathbf{m} \otimes \square_{\mathbf{u}}\mathbf{n}, \quad (17)$$

where \mathbf{m} and \mathbf{n} are any two five-tensor fields.

There is one more constraint that should be imposed on \square , which will enable one to define in a natural way the action of \square on four-vector fields. Namely, one should require that

$$\mathbf{v} \equiv \mathbf{w} \pmod{R} \implies \square_{\mathbf{u}}\mathbf{v} \equiv \square_{\mathbf{u}}\mathbf{w} \pmod{R}, \quad (18)$$

where R is the equivalence relation considered in section 1 of part II. The derivative $\square_{\mathbf{u}}\mathbf{V}$ of an arbitrary four-vector field \mathbf{V} can then be defined as the equivalence class with respect to R of all the fields of the form $\square_{\mathbf{u}}\mathbf{v}$, where $\mathbf{v} \in \mathbf{V}$.

Let us now consider the analogs of connection coefficients for \square . For a given set of five-vector basis fields \mathbf{e}_A , it is natural to define the latter according to the equation

$$\square_A\mathbf{e}_B = \mathbf{e}_C H_{BA}^C, \quad (19)$$

where $\square_A \equiv \square_{\mathbf{e}_A}$. The quantities H^A_{BC} will be called the *five-vector connection coefficients*. If \mathbf{e}_A is a regular basis, then from equation (12) it follows that

$$H^A_{B\mu} = G^A_{B\mu},$$

where $G^A_{B\mu}$ are the connection coefficients associated with ∇ . Furthermore, from condition (18) it follows that in any standard five-vector basis

$$H^\alpha_{5B} = 0 \quad (20)$$

at all α and B . In the usual way one can obtain the transformation formula for five-vector connection coefficients corresponding to the transformation $\mathbf{e}'_A = \mathbf{e}_B L^B_A$:

$$H'^A_{BC} = (L^{-1})^A_D H^D_{EF} L^E_B L^F_C + (L^{-1})^A_D (\partial_F L^D_B) L^F_C.$$

If both bases are standard, one has

$$H'^A_{B5} = (L^{-1})^A_D H^D_{E5} L^E_B L^5_5, \quad (21)$$

so the coefficients H^A_{B5} transform as components of a five-tensor and cannot be nullified at a given space-time point by an appropriate choice of the five-vector basis.

B. Interpretation of the five-vector covariant derivative

In the previous section we have introduced the five-vector covariant derivative and have discussed its basic properties in a formal way. There now arises a natural question: what is the meaning of this derivative?

The very way the operator \square has been introduced in the previous section suggests that the five-vector covariant derivative of an arbitrary five-vector or five-tensor field \mathcal{S} should be regarded as a generalization of the ordinary covariant derivative of \mathcal{S} . From equations (12)–(14) we see that technically this generalization consists in that to the four quantities $\nabla_\alpha \mathcal{S}$, which characterize the variation of \mathcal{S} in the vicinity of a given space-time point and which can be interpreted as derivatives of \mathcal{S} in the direction of the basis five-vectors \mathbf{e}_α , calculated by using certain rules of parallel transport, one adds a fifth quantity, $\square_5 \mathcal{S}$, which depends only on the value of \mathcal{S} at the considered point and which, by itself, cannot be interpreted as a derivative of \mathcal{S} in any direction. These observations lead one to the simplest and the most obvious interpretation of the five-vector covariant derivative where the latter is broken up into a differential and a local part, each of which is then interpreted independently. Since the interpretation of the differential

part of \square , which has all the properties of an ordinary covariant derivative, is quite obvious, the question about the meaning of the five-vector covariant derivative of \mathcal{S} is reduced to the question about the meaning of the quantity $\square_5 \mathcal{S}$: what does it characterize and what role is played by the length of the fifth basis vector?

Having in mind the possible application of \square in physics, for example, in field theory, and assuming that this application consists in replacing the ordinary derivative with the operator \square in the equations of motion and in the expressions for the relevant physical quantities, one can answer the above questions in the following, somewhat formalistic way: the fifth component of the five-vector covariant derivative is just a quantity that appears in the equations of motion and in other physical formulae and which, one may think, expresses some new local properties of space-time; since these formulae involve gradients (exterior derivatives) and not derivatives in some definite directions, in the case of the five-vector covariant derivative, too, one will apparently deal with the operator $\square \equiv \tilde{\omega}^A \square_A$, which does not depend on the choice of the five-vector basis and, in particular, on the length of the fifth basis vector.

It should be noted that within this approach to the interpretation of \square , the parallel transport of vectors is determined only by the differential part of \square , i.e. by the operator ∇ , and consequently has all the usual properties, including the one expressed by equation (7).

There exists another way of interpreting the five-vector covariant derivative where the latter as a whole is regarded as a derivative in some direction, calculated by using certain rules of parallel transport. Since the properties of \square differ from those of the ordinary covariant derivative, it is *a priori* obvious that the properties of the parallel transport associated with \square as a whole should in some way be different from the usual ones. To gain a better understanding of this issue, let us begin by considering a general situation where one is given certain rules of parallel transport, by using which one can evaluate the derivatives of fields, and then determine what properties this transport should have in order that the operator of the derivative it defines could be identified with the operator \square . It seems reasonable to suppose that if such a transport has any physical meaning, then the rules according to which it is performed can in principle be found by analyzing the motion of particles and light rays. In view of this, let us assume that initially one knows only the rules of parallel transport along the timelike and null curves in the positive direction of time. For simplicity, let us consider

the transport of four-vectors, though the analysis presented below will be essentially valid for the case of five-vector transport as well, and even for the case where the transported objects are some kind of abstract vectors or tensors that are not directly related to space-time.

Already at this stage one can say whether or not the considered transport has three important properties: linearity, the property of conserving the inner product g , and torsion. In the following it will always be assumed that parallel transport is linear and conserves g . In that case the absence or existence of torsion can be established by observing whether or not the considered transport coincides with the transport defined by space-time metric (i.e. by the torsion-free g -conserving ordinary covariant derivative, which is uniquely fixed by the metric). In the following I will always allow for arbitrary four-vector torsion (the notion of torsion for five-vectors will be discussed in the next part of the series).

Knowing the considered rules of parallel transport, one can evaluate the derivative of any sufficiently smooth four-vector field along any timelike or null parametrized curve at any point P in space-time. Since one knows the rules of transport only in the positive direction of time, such a derivative, strictly speaking, should be calculated not according to the procedure described in the beginning of the previous section, but according to the procedure where the value of the field at P is compared with its value at the point $\lambda(P) - \Delta\lambda$, and not at the point $\lambda(P) + \Delta\lambda$. The derivative in question will, naturally, depend on the direction of the curve at the considered point and on the rate with which its parameter changes. This dependence will be such that the derivative can be considered a function of the four-vector tangent to the curve. This function will be homogeneous, though not necessarily linear. In the general case, let us denote the operator of this derivative as $D(\mathbf{U})$, where \mathbf{U} is the mentioned tangent four-vector. So far D has been defined only for the timelike and null four-vectors directed towards the future, the set of which will be denoted as V_4^+ .

As it has been said in section A, any derivative defined in such a way has the properties expressed by equations (2c) and (6), where the operator $\nabla_{\mathbf{U}}$ should now be replaced with the operator $D(\mathbf{U})$. Owing to the linearity of the considered transport, this derivative will also have the property expressed by equation (2b), where one should make a similar replacement. To determine the dependence of $D(\mathbf{U})$ on \mathbf{U} more precisely, let us consider at each space-time point the

quantity

$$\Lambda(\mathbf{U}, \mathbf{V}) \equiv D(\mathbf{U} + \mathbf{V}) - D(\mathbf{U}) - D(\mathbf{V}). \quad (22)$$

By virtue of the analog of property (2c) for $D(\mathbf{U})$ and owing to the linear dependence of the derivative $\partial_{\mathbf{U}}$ on its argument, $\Lambda(\mathbf{U}, \mathbf{V})$ is a *local* operator:

$$\Lambda(\mathbf{U}, \mathbf{V})(f\mathbf{W}) = f \cdot \Lambda(\mathbf{U}, \mathbf{V})\mathbf{W}$$

for any scalar function f and any four-vector field \mathbf{W} . It is evident that operator (22) characterizes the relation between the derivatives D in different timelike and null directions. Usually, it is taken that the rules of parallel transport along different curves are correlated with one another in such a way that

$$\Lambda(\mathbf{U}, \mathbf{V}) = 0 \quad (23)$$

for all \mathbf{U} and \mathbf{V} from V_4^+ . The latter equation is evidently nothing but property (7) of the ordinary covariant derivative and means that D depends on its argument linearly. Equation (7) is satisfied necessarily if four-vector torsion is zero.

If equation (23) holds at every point, $D(\mathbf{U})$ is an ordinary covariant derivative, and instead of $D(\mathbf{U})$ I will then write $\nabla_{\mathbf{U}}$. In this case one can define in a natural way the operator $\nabla_{\mathbf{U}}$ for all other \mathbf{U} from V_4 by postulating that parallel transport is reversible:

$$\nabla_{(-\mathbf{U})} = -\nabla_{\mathbf{U}}, \quad (24)$$

and that equation (7) holds for timelike and null four-vectors with *any* time orientation. Since any four-vector can be presented as a sum or difference of two four-vectors from V_4^+ , properties (7) and (24) fix the operator $\nabla_{\mathbf{U}}$ for any \mathbf{U} .

Let us now consider the case where equation (23) is *not* obeyed. Obviously, there exist an infinite number of ways of how this can be so, and though in all cases the operator $\Lambda(\mathbf{U}, \mathbf{V})$ should be a symmetric function of its arguments and have properties like

$$\Lambda(k\mathbf{U}, k\mathbf{V}) = k \cdot \Lambda(\mathbf{U}, \mathbf{V}) \quad (k > 0)$$

and

$$\Lambda(k\mathbf{U}, l\mathbf{U}) = 0 \quad (k, l > 0),$$

which evidently follow from definition (22), these constraints limit the possible form of $\Lambda(\mathbf{U}, \mathbf{V})$ very little. To obtain a derivative that could be identified with \square , let us consider one of the simplest cases where for all \mathbf{U} and \mathbf{V} from V_4^+ the operator $\Lambda(\mathbf{U}, \mathbf{V})$ is *proportional to the same local operator*. It is evident that the normalization of the latter can be chosen arbitrarily. Let us suppose that we have fixed it somehow, and let us denote the corresponding operator as Δ . The

above assertion about $\Lambda(\mathbf{U}, \mathbf{V})$ can then be expressed in the following way:

$$\Lambda(\mathbf{U}, \mathbf{V}) = \phi(\mathbf{U}, \mathbf{V}) \cdot \Delta, \quad (25)$$

where $\phi(\mathbf{U}, \mathbf{V})$ is some real-valued symmetric function of two four-vectors from V_4^+ , which has several other properties that follow from the properties of $\Lambda(\mathbf{U}, \mathbf{V})$ mentioned above. Naturally, at different points in space-time the function $\phi(\mathbf{U}, \mathbf{V})$ and the operator Δ itself may be different.

Let us select a basis in the tangent space of four-vectors at the considered point in such a way that all $\mathbf{E}_\alpha \in V_4^+$. Let us choose an arbitrary four-vector $\mathbf{U} = U^\alpha \mathbf{E}_\alpha$ from V_4^+ and consider for it the quantity

$$D(\mathbf{U}) - U^\alpha D(\mathbf{E}_\alpha).$$

By using equation (25) it is not difficult to prove that for any such \mathbf{U} the above quantity is proportional to Δ . Denoting the proportionality factor as $\varrho(\mathbf{U})$, one can write:

$$D(\mathbf{U}) = U^\alpha \Delta_\alpha + \varrho(\mathbf{U}) \cdot \Delta, \quad (26)$$

where $\Delta_\alpha \equiv D(\mathbf{E}_\alpha)$. Consequently, the set of operators $D(\mathbf{U})$ for all $\mathbf{U} \in V_4^+$ at the considered point is a subset of some five-dimensional real vector space.

From equation (26) it follows that $\varrho(\mathbf{U})$ is a homogeneous function of \mathbf{U} , since this is true of the first term in the right-hand side of (26) and of the operator $D(\mathbf{U})$ itself. However, the dependence of $\varrho(\mathbf{U})$ on \mathbf{U} cannot be linear, since in that case the operator $D(\mathbf{U})$ would also be linear in \mathbf{U} , and $\varrho(\mathbf{U})$ would be identically zero. Therefore, in equation (26) the operator $D(\mathbf{U})$ is presented as a sum of a term linear in \mathbf{U} and of a term proportional to Δ and depending on \mathbf{U} nonlinearly. It is evident that such a decomposition is not unique. Indeed, one can write that

$$D(\mathbf{U}) = U^\alpha \Delta'_\alpha + \varrho'(\mathbf{U}) \cdot \Delta,$$

where

$$\Delta'_\alpha = \Delta_\alpha + X_\alpha \cdot \Delta \quad (27a)$$

$$\varrho'(\mathbf{U}) = \varrho(\mathbf{U}) - U^\alpha X_\alpha, \quad (27b)$$

and X_α are arbitrary constants. The function ϱ' has the same formal properties as ϱ . Moreover, if instead of the basis \mathbf{E}_α one selects some other four-vector basis, \mathbf{E}'_α , also made only of vectors from V_4^+ , then, as one can easily prove, the function ϱ' corresponding to it will be related to ϱ by a transformation of the form (27b). From equation (26) it follows that the function ϱ corresponding to a given basis \mathbf{E}_α satisfies the condition

$$\varrho(\mathbf{E}_\alpha) = 0 \text{ for all } \alpha.$$

It is easy to see that the function ϕ introduced above is expressed in terms of ϱ as follows:

$$\phi(\mathbf{U}, \mathbf{V}) = \varrho(\mathbf{U} + \mathbf{V}) - \varrho(\mathbf{U}) - \varrho(\mathbf{V}), \quad (28)$$

and is invariant, as it should be, under transformation (27b). From formula (28) and the homogeneity of ϱ follow the symmetry of ϕ and all its other properties that can be derived from definition (22). Therefore, equation (26) does not impose any constraints on ϱ except for homogeneity. Other than that this function can be absolutely arbitrary.

To obtain a derivative that can be identified with \square , let us impose one more constraint on the considered transport of four-vectors, which can be substantiated by the following arguments.

One should observe that in its structure, the expression in the right-hand side of formula (26) is a contraction of the five numbers $U^0, U^1, U^2, U^3, \varrho(\mathbf{U})$ with the five operators $\Delta_0, \Delta_1, \Delta_2, \Delta_3, \Delta$. The first four numbers characterize only the direction and parametrization of the curve along which the derivative is calculated, and do not depend in any way on the rules of parallel transport, all the information about which (in this part of $D(\mathbf{U})$) is contained in the quantities Δ_α . Considering this, it seems natural to examine the case where $\varrho(\mathbf{U})$, too, is independent of the transport rules and is only a characteristic of the curve. Though formally this assumption does not place any limitations on the form of $\varrho(\mathbf{U})$, in fact it means that at every point in space-time the latter should be invariant under active Lorentz transformations in the tangent space of four-vectors, since otherwise space-time would acquire a local anisotropy of unknown origin, which physically is not a very appealing idea. Since the decomposition of D into a linear and a nonlinear part is not unique, the above assertion about the invariance of ϱ should be formulated as follows: there exists such a choice of the constants X_α in formula (27b) that the function ϱ' obtained by this transformation is invariant under the mentioned active transformations in V_4 . Since in addition to this, $\varrho'(\mathbf{U})$ is a homogeneous function of \mathbf{U} , it should simply be proportional to the length of \mathbf{U} . The proportionality factor can be absorbed into the operator Δ , whose normalization up to this point has been arbitrary, so at an appropriate choice of X_α one will have

$$D(\mathbf{U}) = U^\alpha \Delta'_\alpha + \|\mathbf{U}\| \cdot \Delta, \quad (29)$$

where $\|\mathbf{U}\| \equiv \sqrt{g(\mathbf{U}, \mathbf{U})}$ and the operators Δ'_α are given by formula (27a). It is easy to prove that owing to the nonlinear dependence of $\|\mathbf{U}\|$ on \mathbf{U} , the function $\varrho'(\mathbf{U})$ can be proportional to $\|\mathbf{U}\|$ only at one particular choice of the constants X_α .

Up to now we have considered the operator D a function of the tangent four-vector. Since V_4 is isomorphic to \mathcal{Z} , one can just as well consider D a function of the five-vector from \mathcal{Z} that corresponds to the tangent four-vector. One can then repeat the analysis made in this section and obtain the analogs of all the formulae presented above, where instead of the four-vectors from V_4^+ there will now stand the corresponding five-vectors from \mathcal{Z} , the set of which will be denoted as \mathcal{Z}^+ . In particular, the analogs of formulae (27) will have the form

$$\Delta'_\alpha = \Delta_\alpha + X_\alpha \cdot \Delta \quad (30a)$$

$$\varrho'(\mathbf{u}) = \varrho(\mathbf{u}) - u^\alpha X_\alpha, \quad (30b)$$

where $\Delta_\alpha \equiv D(\mathbf{e}_\alpha)$, \mathbf{e}_α is some basis in \mathcal{Z} consisting only of five-vectors from \mathcal{Z}^+ , and u^α are the components of the arbitrary five-vector $\mathbf{u} \in \mathcal{Z}^+$ in this basis. Formula (29) will acquire the form

$$D(\mathbf{u}) = u^\alpha \Delta'_\alpha + \|\mathbf{u}\| \cdot \Delta, \quad (31)$$

where $\|\mathbf{u}\| \equiv \sqrt{g(\mathbf{u}, \mathbf{u})}$. It should be noted that the operator Δ can be found from the equation

$$\Lambda(\mathbf{u}, \mathbf{v}) = (\|\mathbf{u} + \mathbf{v}\| - \|\mathbf{u}\| - \|\mathbf{v}\|) \cdot \Delta$$

at any such \mathbf{u} and \mathbf{v} from \mathcal{Z}^+ that the expression in the brackets in the right-hand side does not vanish. The operators Δ'_α can be found according to the formula

$$\Delta'_\alpha = D(\mathbf{e}_\alpha) - \|\mathbf{e}_\alpha\| \cdot \Delta. \quad (32)$$

In the general case, the operator $D(\mathbf{u})$ is a nonlinear function of \mathbf{u} . As is seen from formula (31), one can make the dependence of D on its argument linear if instead of considering it a function of $\mathbf{u} \in \mathcal{Z}^+$, one formally regards it as a function of a five-vector whose \mathcal{Z} -component coincides with \mathbf{u} and whose \mathcal{E} -component is proportional to $\|\mathbf{u}\|$. Denoting this latter five-vector as $\check{\mathbf{u}}$, from dimensional considerations one finds that $\check{\mathbf{u}}^\mathcal{E}$ should equal $\|\mathbf{u}\| \cdot k\mathbf{n}$, where \mathbf{n} is the normalized five-vector from \mathcal{E} introduced in part II and k can be any nonzero real number. Without any loss in generality one can put $k = 1$, considering this a part of the definition of $\check{\mathbf{u}}$. Thus, one will have

$$\check{\mathbf{u}} = \mathbf{u} + \|\mathbf{u}\| \cdot \mathbf{n}. \quad (33)$$

One can regard $\check{\mathbf{u}}$ as a tangent vector of a new type. Considering that it is a homogeneous function of the directional derivative operator, one may call it a *homogeneous* tangent five-vector. It is easy to see that $\check{\mathbf{u}}$ satisfies the relation

$$h(\check{\mathbf{u}}, \check{\mathbf{u}}) = (1 + \text{sign}\xi) \cdot g(\check{\mathbf{u}}, \check{\mathbf{u}}), \quad (34)$$

which can be used as a condition that fixes the \mathcal{E} -component of $\check{\mathbf{u}}$ up to a sign.

To distinguish the operator D regarded as a function of a five-vector from \mathcal{Z}^+ from the same operator regarded as a function of a homogeneous tangent five-vector, in the second case instead of D I will use the symbol \mathcal{D} . Initially, the operator \mathcal{D} is defined only for the five-vectors of the form (33) with $\mathbf{u} \in \mathcal{Z}^+$. One can then define it for all other five-vectors by linearity, i.e. supposing that for any $\mathbf{w} \in V_5$

$$\mathcal{D}(\mathbf{w}) = w^\alpha \Delta'_\alpha + w^5 \Delta,$$

where w^A are the components of \mathbf{w} in the normalized regular basis \mathbf{e}'_A whose first four elements coincide with the basis vectors \mathbf{e}_α from \mathcal{Z}^+ considered above. Then, for Δ'_α and Δ one will have

$$\Delta'_\alpha = \mathcal{D}(\mathbf{e}'_\alpha) \quad \text{and} \quad \Delta = \mathcal{D}(\mathbf{e}'_5).$$

In a similar manner, from the definition of operators Δ_α and equation (32) one obtains

$$\Delta_\alpha = \mathcal{D}(\mathbf{e}'_\alpha - X_\alpha \mathbf{e}'_5),$$

where $X_\alpha = -\|\mathbf{e}'_\alpha\|$. In the light of these relations, formulae (30) acquire a new meaning: formula (30a) expresses the operator $\mathcal{D}(\mathbf{e}'_\alpha)$ in terms of operators $\mathcal{D}(\mathbf{e}''_\alpha)$ and $\mathcal{D}(\mathbf{e}''_5)$, where $\mathbf{e}''_\alpha = \mathbf{e}'_\alpha - X_\alpha \mathbf{e}'_5$ and $\mathbf{e}''_5 = \mathbf{e}'_5$, and equation (27b) is the transformation formula for the fifth component of $\check{\mathbf{u}}$ corresponding to the transformation from the basis \mathbf{e}''_A to the basis \mathbf{e}'_A .

Up to now we have been talking about the transport of four-vectors. In an absolutely similar way we could have considered the transport of five-vectors and would have obtained the derivative D or \mathcal{D} defined for five-vector fields. I have preferred to deal with four-vectors because the situation with their parallel transport is simpler: this transport can be absolutely arbitrary as long as it conserves the linear operations and the inner product g . As for the transport of five-vectors, so far we have considered only one particular case, examined in section 3 of part II, and have not yet discussed what requirements—in addition to linearity, conservation of g , and preservation of the equivalence relation R —this transport should satisfy in the general case. This uncertainty is of no importance to our analysis though, since here we are concerned only with the *relation* between the derivatives of fields in different space-time directions.

Repeating the analysis performed above for the case of five-vector parallel transport, one will obtain a derivative \mathcal{D} whose operator will have the same formal properties as \square . Indeed, for five-vector fields \mathcal{D} will be a map from $\mathcal{F} \times \mathcal{F}$ to \mathcal{F} , which, as has

been said above, will have properties (11b), (11c), and (15), and, owing to the linear dependence of \mathcal{D} on its argument, also property (11a). If in addition to this the transport of five-vectors conserves the contraction and tensor product and preserves the equivalence relation R , then \mathcal{D} will also have properties (16), (17), and (18). The derivative \square can therefore be interpreted as a derivative in a certain direction, calculated by using certain rules of parallel transport whose properties differ from the usual ones. From now on, instead of \mathcal{D} I will write \square .

When deriving the properties of \square from the properties of the corresponding transport, it is convenient to use the following proposition: if equation

$$\square_{\mathbf{v}}\mathcal{S} = 0,$$

where \mathcal{S} can be a field of arbitrary nature, holds for any homogeneous tangent five-vector \mathbf{v} with $\mathbf{v}^{\mathcal{Z}} \in \mathcal{Z}^+$, then it also holds for *any* \mathbf{v} from V_5 . This theorem follows evidently from the fact that \square is a linear function of its argument and the fact that one can select a basis in V_5 consisting only of homogeneous tangent five-vectors with the \mathcal{Z} -component belonging to \mathcal{Z}^+ . By using this theorem one can easily show that from the conservation of g by the considered transport of five-vectors follows the equation

$$\square g = 0, \quad (35)$$

in which g is regarded as a five-tensor. From this equation follow certain constraints on the five-vector connection coefficients H_{BC}^A , which are similar to those constraints on the four-vector connection coefficients that follow from the equation $\nabla g = 0$.

In conclusion, let me say a few words about the definition of the transport corresponding to \square for the timelike and null curves directed towards the past and for the spacelike curves. From everything that has been said above it is apparent that the problem actually comes to selecting for the mentioned curves the homogeneous tangent five-vector.

Ordinary parallel transport is reversible, which means that the derivative corresponding to it changes its sign whenever the parameterization of the curve is changed for the opposite ($\lambda \rightarrow -\lambda$). If the same requirement is imposed on the transport corresponding to \square , then the homogeneous tangent five-vector corresponding to a timelike or null curve directed towards the past will be given by the formula

$$\check{\mathbf{u}} = \mathbf{u} - \|\mathbf{u}\| \cdot \mathbf{n},$$

and not by formula (33). For spacelike curves the \mathcal{E} -component of $\check{\mathbf{u}}$ will be zero altogether, since on the

one hand, it should change sign whenever the parameterization of the curve is reversed, and on the other hand, it should remain the same since the tangent four-vectors corresponding to these two parameterizations can be transformed one into the other by a Lorentz transformation. The latter means that for spacelike curves the transport associated with \square will coincide with the transport corresponding only to the differential part of \square .

This asymmetry in the definition of the homogeneous tangent vector between the spacelike and non-spacelike curves and between the curves directed towards the future and towards the past may be interpreted as an indication to that in the case of parallel transport associated with \square the condition of reversibility should not be imposed. Instead, one can postulate that for all types of curves the homogeneous tangent five-vector is given by formula (33), where for the spacelike curves $\|\mathbf{u}\|$ means $\sqrt{-g(\mathbf{U}, \mathbf{U})}$. The corresponding transport will differ from the ordinary one by an additional rotation of the transported vectors, which will not depend on the direction of the transport but only on the length of the travelled path, and it is this additional twist that will produce the “local” part of the operator \square .

C. Five-vector covariant derivative for fields of nonspacetime vectors and tensors

The five-vector covariant derivative can also be defined for the fields whose values are some kind of abstract vectors or tensors that have no direct relation to the space-time manifold. In the following such vectors and tensors will be referred to as *nonspacetime* vectors and tensors.

Let us consider a set \mathcal{V} of fields whose values are some n -dimensional nonspacetime vectors, which will be denoted with small capital Roman letters with an arrow: $\vec{A}, \vec{B}, \vec{C}$, etc. Defining an ordinary covariant derivative for such fields is equivalent to fixing a map

$$\nabla : \mathcal{D} \times \mathcal{V} \rightarrow \mathcal{V},$$

or an equivalent map

$$\nabla : \mathcal{F}_{\mathcal{Z}} \times \mathcal{V} \rightarrow \mathcal{V}, \quad (36)$$

which should satisfy three requirements similar to requirements (2) for map (1). If \vec{E}_i ($i = 1, \dots, n$) is some set of basis fields in \mathcal{V} , then the corresponding connection coefficients, which are called gauge fields in physics, are defined by the equation

$$\nabla_{\mu} \vec{E}_i = \vec{E}_j A_{i\mu}^j. \quad (37)$$

In a similar manner one can formally define the five-vector covariant derivative for the fields from \mathcal{V} . This is equivalent to fixing a map

$$\square : \mathcal{F} \times \mathcal{V} \rightarrow \mathcal{V}, \quad (38)$$

which will be regarded as an extension of map (36), so in this case, too, the operators \square and ∇ will be related as in equation (12). In addition to this, map (38) should satisfy three requirements similar to requirements (11) for five-vector fields, which I will not present here.

The connection coefficients corresponding to derivative (38), which I will call *five-vector gauge fields*, are defined by the equation

$$\square_A \vec{e}_i = \vec{e}_j B_{iA}^j. \quad (39)$$

It is apparent that in any regular five-vector basis

$$B_{j\mu}^i = A_{j\mu}^i$$

for any i, j , and μ . In the usual manner one can obtain the formula for transformation of five-vector gauge fields under the transformation $\vec{e}'_i = \vec{e}_j L_i^j$ of the basis fields in \mathcal{V} :

$$B'_{jA}{}^i = (L^{-1})^i{}_k B_{iA}^k L_j^l + (L^{-1})^i{}_k \partial_A L_j^k.$$

From this formula it follows that in any standard five-vector basis

$$B'_{j5}{}^i = (L^{-1})^i{}_k B_{i5}^k L_j^l, \quad (40)$$

so the fields B_{j5}^i transform as components of a tensor of rank $(1, 1)$ over \mathcal{V} . This latter fact, together with the facts that B_{j5}^i are Lorentz scalars and that in the equations of motion for matter fields they will appear at the place where the mass parameter usually stands, may suggest that some of these new gauge fields can effectively play the role of Higgs fields.

Let us now suppose that for the considered type of nonspacetime vectors there exists a certain nondegenerate inner product θ . If this inner product is conserved by the parallel transport associated with \square , then from considerations similar to those that have led to equation (35) it follows that

$$\square_A \theta = 0,$$

where θ is regarded as a tensor over \mathcal{V} . This equation imposes certain constraints on the five-vector gauge fields. For example, if the inner product is Hermitian, these fields should be such that

$$\partial_A \theta_{ij} - \theta_{kj} (B_{iA}^k)^* - \theta_{ik} B_{jA}^k = 0, \quad (41)$$

where $*$ denotes complex conjugation. If at each point in space-time the basis \vec{e}_i is selected orthonormal, then from the latter equation one obtains that

$$\theta_{kj} (B_{iA}^k)^* + \theta_{ik} B_{jA}^k = 0,$$

which means that the quantities $B_{ijA} \equiv \theta_{ik} B_{jA}^k$ are anti-Hermitian matrices with respect to the indices i and j .

D. Exterior derivative of nonscalar-valued forms

In applications of exterior differential calculus one often has to deal with forms whose values are not scalars but are some vector-like objects: four-vectors or four-tensors; spinors; some kind of nonspacetime vectors or tensors; or tensor products of such objects. To this list one can now add five-vectors and five-tensors.

For obvious reasons, in the general case an arbitrary nonscalar-valued form $\tilde{\mathbf{S}}$ cannot be integrated over a finite volume of appropriate dimension directly. The integration can be performed if before that one contracts $\tilde{\mathbf{S}}$ with a field of appropriate type, so that their contraction would be a scalar-valued form. A more general possibility is to construct the wedge product of $\tilde{\mathbf{S}}$ with some other form $\tilde{\mathbf{T}}$ whose values are tensors complementary to those which are the values of $\tilde{\mathbf{S}}$ (i.e. tensors that can be contracted with the value of $\tilde{\mathbf{S}}$ to produce a scalar) and then contract the values of $\tilde{\mathbf{S}}$ and $\tilde{\mathbf{T}}$. In the following this sort of expressions will be denoted as

$$\langle \tilde{\mathbf{S}} \wedge \tilde{\mathbf{T}} \rangle.$$

By definition, the contraction over the values does not affect those indices of $\tilde{\mathbf{S}}$ and $\tilde{\mathbf{T}}$ over which they are contracted with multivectors that characterize the infinitesimal integration volumes and with respect to which they are antisymmetrized when one constructs their wedge product. Thus, in the case of nonscalar-valued forms we will be dealing with integrals of the form

$$\int_V \langle \tilde{\mathbf{S}} \wedge \tilde{\mathbf{T}} \rangle.$$

The calculus of nonscalar-valued five-vector forms is very similar to the calculus of their four-vector counterparts. In view of this, it will be convenient to recall first the basic definitions and formulae for forms of the latter type and then to comment on the corresponding formulae for five-vector forms.

An arbitrary nonscalar-valued four-vector m -form $\tilde{\mathbf{S}}$ can be presented as

$$\tilde{\mathbf{S}} = \tilde{\mathbf{S}}_{|\alpha_1 \dots \alpha_m|} \mathbf{d}x^{\alpha_1} \wedge \dots \wedge \mathbf{d}x^{\alpha_m},$$

where the components $\tilde{\mathbf{S}}_{\alpha_1 \dots \alpha_m}$ are elements of some vector or tensor space. The wedge product of this m -form with some other four-vector n -form

$$\tilde{\mathbf{T}} = \tilde{\mathbf{T}}_{|\alpha_1 \dots \alpha_n|} \mathbf{d}x^{\alpha_1} \wedge \dots \wedge \mathbf{d}x^{\alpha_n},$$

whose values can be quantities of a totally different nature than those of $\tilde{\mathbf{S}}$, is the $(m+n)$ -form

$$\begin{aligned} \tilde{\mathbf{S}} \wedge \tilde{\mathbf{T}} &= (\tilde{\mathbf{S}}_{|\alpha_1 \dots \alpha_m|} \otimes \tilde{\mathbf{T}}_{|\alpha_{m+1} \dots \alpha_{m+n}|}) \\ &\quad \times \mathbf{d}x^{\alpha_1} \wedge \dots \wedge \mathbf{d}x^{\alpha_{m+n}}. \end{aligned}$$

If the values of $\tilde{\mathbf{T}}$ are tensors complementary to those which are the values of $\tilde{\mathbf{S}}$, one can contract $\tilde{\mathbf{S}}$ and $\tilde{\mathbf{T}}$ over the values and obtain the scalar-valued form

$$\begin{aligned} \prec \tilde{\mathbf{S}} \wedge \tilde{\mathbf{T}} \succ &= \prec \tilde{\mathbf{S}}_{|\alpha_1 \dots \alpha_m|}, \tilde{\mathbf{T}}_{|\alpha_{m+1} \dots \alpha_{m+n}|} \succ \\ &\quad \times \mathbf{d}x^{\alpha_1} \wedge \dots \wedge \mathbf{d}x^{\alpha_{m+n}}. \end{aligned} \quad (42)$$

According to definition (12) of part IV, the exterior derivative of form (42) equals

$$\begin{aligned} \mathbf{d} \prec \tilde{\mathbf{S}} \wedge \tilde{\mathbf{T}} \succ &= \partial_\alpha \prec \tilde{\mathbf{S}}_{|\alpha_1 \dots \alpha_m|}, \tilde{\mathbf{T}}_{|\alpha_{m+1} \dots \alpha_{m+n}|} \succ \\ &\quad \times \mathbf{d}x^\alpha \wedge \mathbf{d}x^{\alpha_1} \wedge \dots \wedge \mathbf{d}x^{\alpha_{m+n}}. \end{aligned}$$

By using the Leibniz rule for the operator ∇ , one can present this derivative as

$$\mathbf{d} \prec \tilde{\mathbf{S}} \wedge \tilde{\mathbf{T}} \succ = \prec \mathbf{d}\tilde{\mathbf{S}} \wedge \tilde{\mathbf{T}} \succ + (-1)^m \prec \tilde{\mathbf{S}} \wedge \mathbf{d}\tilde{\mathbf{T}} \succ, \quad (43)$$

where, by definition,

$$\mathbf{d}\tilde{\mathbf{S}} \equiv \nabla_\alpha \tilde{\mathbf{S}}_{|\alpha_1 \dots \alpha_m|} \mathbf{d}x^\alpha \wedge \mathbf{d}x^{\alpha_1} \wedge \dots \wedge \mathbf{d}x^{\alpha_m}, \quad (44)$$

and the derivative $\mathbf{d}\tilde{\mathbf{T}}$ is defined in a similar way. Form (44) of rank $m+1$ is called the exterior derivative of the nonscalar-valued four-vector m -form $\tilde{\mathbf{S}}$.

From the latter definition it follows that for an arbitrary nonscalar field $\tilde{\mathbf{F}}$ regarded as a four-vector 0-form, $\mathbf{d}\tilde{\mathbf{F}}$ is such a nonscalar-valued 1-form that

$$\langle \mathbf{d}\tilde{\mathbf{F}}, \mathbf{U} \rangle = \nabla_\mathbf{U} \tilde{\mathbf{F}}$$

for any four-vector \mathbf{U} , which is the analog of formula (10) of part IV. Using this relation, one can write:

$$\mathbf{d}\tilde{\mathbf{S}} = \mathbf{d}\tilde{\mathbf{S}}_{|\alpha_1 \dots \alpha_m|} \wedge \mathbf{d}x^{\alpha_1} \wedge \dots \wedge \mathbf{d}x^{\alpha_m},$$

which is the analog of formula (12) of part IV. The exterior derivative of $\tilde{\mathbf{S}}$ can also be defined in a manner similar to formulae (14) of part IV: if $\tilde{\mathbf{S}}$ is a 1-form, then $\mathbf{d}\tilde{\mathbf{S}}$ is such a 2-form that

$$\begin{aligned} \langle \mathbf{d}\tilde{\mathbf{S}}, \mathbf{U} \wedge \mathbf{V} \rangle &= \nabla_\mathbf{U} \langle \tilde{\mathbf{S}}, \mathbf{V} \rangle \\ &\quad - \nabla_\mathbf{V} \langle \tilde{\mathbf{S}}, \mathbf{U} \rangle - \langle \tilde{\mathbf{S}}, [\mathbf{U}, \mathbf{V}] \rangle \end{aligned} \quad (45a)$$

for any two four-vector fields \mathbf{U} and \mathbf{V} ; if $\tilde{\mathbf{S}}$ is a 2-form, then $\mathbf{d}\tilde{\mathbf{S}}$ is such a 3-form that

$$\begin{aligned} &\langle \mathbf{d}\tilde{\mathbf{S}}, \mathbf{U} \wedge \mathbf{V} \wedge \mathbf{W} \rangle \\ &= \nabla_\mathbf{U} \langle \tilde{\mathbf{S}}, \mathbf{V} \wedge \mathbf{W} \rangle + \nabla_\mathbf{V} \langle \tilde{\mathbf{S}}, \mathbf{W} \wedge \mathbf{U} \rangle \\ &\quad + \nabla_\mathbf{W} \langle \tilde{\mathbf{S}}, \mathbf{U} \wedge \mathbf{V} \rangle - \langle \tilde{\mathbf{S}}, [\mathbf{U}, \mathbf{V}] \wedge \mathbf{W} \rangle \\ &\quad - \langle \tilde{\mathbf{S}}, [\mathbf{V}, \mathbf{W}] \wedge \mathbf{U} \rangle - \langle \tilde{\mathbf{S}}, [\mathbf{W}, \mathbf{U}] \wedge \mathbf{V} \rangle \end{aligned} \quad (45b)$$

for any four-vector fields \mathbf{U} , \mathbf{V} and \mathbf{W} ; etc. It is not difficult to see that for nonscalar-valued forms one can use formula (13a) of part IV for the exterior derivative of a wedge product. However, in the general case the double derivative $\mathbf{d}\mathbf{d}\tilde{\mathbf{S}}$ of an arbitrary nonscalar-valued form $\tilde{\mathbf{S}}$ is not identically zero.

Everything that has been said above about four-vector forms applies, with obvious modification, to five-vector forms as well. An essentially new feature here is that for an arbitrary nonscalar-valued five-vector m -form

$$\tilde{\mathbf{t}} = \tilde{\mathbf{t}}_{|A_1 \dots A_m|} \tilde{\mathbf{o}}^{A_1} \wedge \dots \wedge \tilde{\mathbf{o}}^{A_m} \quad (46)$$

($\tilde{\mathbf{o}}^A$ is a basis of five-vector 1-forms dual to some passive regular coordinate five-vector basis) one can define *two* exterior derivatives:

$$\nabla_A \tilde{\mathbf{t}}_{|A_1 \dots A_m|} \tilde{\mathbf{o}}^A \wedge \tilde{\mathbf{o}}^{A_1} \wedge \dots \wedge \tilde{\mathbf{o}}^{A_m} \quad (47)$$

and

$$\square_A \tilde{\mathbf{t}}_{|A_1 \dots A_m|} \tilde{\mathbf{o}}^A \wedge \tilde{\mathbf{o}}^{A_1} \wedge \dots \wedge \tilde{\mathbf{o}}^{A_m}. \quad (48)$$

Both of these derivatives are well-defined and both may be of use in calculations. In the following I will use the symbol \mathbf{d} to denote derivative (48) and will refer to it simply as to the exterior derivative of $\tilde{\mathbf{t}}$. For derivative (47) I will introduce the notation \mathbf{d}^∇ . It is easy to see that for any $\tilde{\mathbf{t}}$ the derivatives $\mathbf{d}\tilde{\mathbf{t}}$ and $\mathbf{d}^\nabla \tilde{\mathbf{t}}$ differ by $(\mathbf{d}\tilde{\mathbf{t}}^\mathcal{Z})^\mathcal{E}$.

It is not difficult to obtain for \mathbf{d} and \mathbf{d}^∇ the analogs of formulae (19) and (21) of part IV, where instead of operators ∂ there will now stand operators \square and ∇ , respectively. Formulae (20) and (22a) of part IV will apply to nonscalar-valued forms without any changes, however, in the general case, identity (22b) will no longer be valid.

E. Five-vector analogs of the field strength tensor

As is known, the action of the operator $\mathbf{d}\mathbf{d}$ on an arbitrary nonscalar-valued four-vector form $\tilde{\mathbf{S}}$ of rank less than 3 does not produce an identical zero. Instead, it produces a form which is the wedge product of $\tilde{\mathbf{S}}$ with a certain 2-form, \mathcal{R} , whose values are linear algebraic operators that act upon the values of $\tilde{\mathbf{S}}$. The operator-valued 2-form \mathcal{R} is the same for all

forms whose values belong to the same vector or tensor space, and does not depend on the rank of the form. If the values of $\tilde{\mathbf{S}}$ are elements of the tensor product of vector spaces W_1, W_2, \dots, W_n , then the 2-form \mathcal{R} corresponding to $\tilde{\mathbf{S}}$ can be constructed according to a simple recipe from the 2-forms \mathcal{R} that correspond to the forms whose values are elements of W_1, W_2, \dots, W_n . If the values of $\tilde{\mathbf{S}}$ are linear forms associated with some vector space W , then the corresponding 2-form \mathcal{R} differs only in the sign and transposition from the 2-form \mathcal{R} that corresponds to those forms whose values are elements of W . Finally, for the scalar-valued forms \mathcal{R} is identically zero, which manifests itself in identity (13b) of part IV.

We thus see that to be able to evaluate the double exterior derivatives of arbitrary nonscalar-valued forms it is sufficient to know the operator-valued 2-forms \mathcal{R} only for the 0-forms and only for those of them whose values are *vectors* (not tensors). As is known, the 2-form \mathcal{R} that corresponds to four-vectors is called the curvature tensor and is denoted as \mathbf{R} . The 2-forms \mathcal{R} that correspond to nonspacetime vectors are called field strength tensors and are usually denoted as \mathbf{F} or \mathbf{G} .

Everything that has been said above is true of nonscalar-valued five-vector forms as well. In this section I will consider the five-vector analogs of the field strength tensors and will discuss their basic properties. The five-vector analog of the curvature tensor will be discussed in the next part of the series.

Since in the case of nonscalar-valued five-vector forms one has *two* exterior derivative operators, \mathbf{d}^∇ and \mathbf{d} , one can consider two five-vector analogs of the field strength tensor, which will be denoted as \mathbf{F}^∇ and \mathbf{F} , respectively. As in section C, let us consider a certain set of fields whose values are some nonspacetime vectors. Regarding these fields as nonscalar-valued five-vector 0-forms, for an arbitrary field \vec{s} one has

$$\langle \mathbf{d}^\nabla \vec{s}, \mathbf{w} \rangle = \nabla_{\mathbf{w}} \vec{s}.$$

Substituting this expression into the analog of formula (45a) for five-vector forms, one finds that for any two five-vector fields \mathbf{u} and \mathbf{v}

$$\begin{aligned} \langle \mathbf{d}^\nabla \mathbf{d}^\nabla \vec{s}, \mathbf{u} \wedge \mathbf{v} \rangle &= \nabla_{\mathbf{u}} \langle \mathbf{d}^\nabla \vec{s}, \mathbf{v} \rangle \\ &\quad - \nabla_{\mathbf{v}} \langle \mathbf{d}^\nabla \vec{s}, \mathbf{u} \rangle - \langle \mathbf{d}^\nabla \vec{s}, [\mathbf{u}, \mathbf{v}] \rangle \\ &= (\nabla_{\mathbf{u}} \nabla_{\mathbf{v}} - \nabla_{\mathbf{v}} \nabla_{\mathbf{u}} - \nabla_{[\mathbf{u}, \mathbf{v}]}) \vec{s} \\ &\equiv \mathbf{F}^\nabla(\mathbf{u} \wedge \mathbf{v}) \vec{s}. \end{aligned}$$

It is evident that operator $\mathbf{F}^\nabla(\mathbf{u} \wedge \mathbf{v})$ depends only on the \mathcal{Z} -components of \mathbf{u} and \mathbf{v} . If $\mathbf{u} \in \mathbf{U}$ and $\mathbf{v} \in \mathbf{V}$, then $\nabla_{\mathbf{u}} = \nabla_{\mathbf{U}}$, $\nabla_{\mathbf{v}} = \nabla_{\mathbf{V}}$ and $\nabla_{[\mathbf{u}, \mathbf{v}]} = \nabla_{[\mathbf{U}, \mathbf{V}]}$, and the right-hand side will equal

$$(\nabla_{\mathbf{U}} \nabla_{\mathbf{V}} - \nabla_{\mathbf{V}} \nabla_{\mathbf{U}} - \nabla_{[\mathbf{U}, \mathbf{V}]}) \vec{s},$$

which is the usual expression for the four-vector field strength tensor, so $\mathbf{F}^\nabla(\mathbf{u} \wedge \mathbf{v})$ is simply the five-vector equivalent of the latter. Among other things this means that \mathbf{F}^∇ is a local operator. The result of its action on an arbitrary field $\vec{s} = s^i \vec{e}_i$ is expressed in components as

$$(\mathbf{F}^\nabla \vec{s})^i_{AB} = F^{(\nabla)i}_{jAB} s^j, \quad (49)$$

and it is not difficult to see that

$$F^{(\nabla)i}_{j\alpha 5} = F^{(\nabla)i}_{j5\alpha} = 0 \quad (50)$$

and that in any standard coordinate basis

$$\begin{aligned} F^{(\nabla)i}_{j\alpha\beta} &= \partial_\alpha A^i_{j\beta} - \partial_\beta A^i_{j\alpha} \\ &\quad + A^i_{k\alpha} A^k_{j\beta} - A^i_{k\beta} A^k_{j\alpha}, \end{aligned} \quad (51)$$

where $A^i_{j\alpha}$ are the gauge fields that correspond to the basis fields \vec{e}_i .

Performing the same calculations with the operator \mathbf{d} , one obtains that

$$\begin{aligned} \langle \mathbf{d} \vec{s}, \mathbf{u} \wedge \mathbf{v} \rangle \\ = (\square_{\mathbf{u}} \square_{\mathbf{v}} - \square_{\mathbf{v}} \square_{\mathbf{u}} - \square_{[\mathbf{u}, \mathbf{v}]}) \vec{s} \equiv \mathbf{F}(\mathbf{u} \wedge \mathbf{v}) \vec{s}, \end{aligned}$$

where $\mathbf{F}(\mathbf{u} \wedge \mathbf{v})$ can be shown to be a linear algebraic operator and is a contraction of a certain operator-valued 2-form \mathbf{F} with the bivector $\mathbf{u} \wedge \mathbf{v}$. An equivalent expression for \mathbf{F} can be obtained by using definition (48). In components, the effect of \mathbf{F} on an arbitrary 0-form \vec{s} is given by a formula similar to formula (49):

$$(\mathbf{F} \vec{s})^i_{AB} = F^i_{jAB} s^j,$$

and instead of (50) and (51) one now has

$$\begin{aligned} F^i_{jAB} &= \partial_A B^i_{jB} - \partial_B B^i_{jA} \\ &\quad + B^i_{kA} B^k_{jB} - B^i_{kB} B^k_{jA}, \end{aligned} \quad (52)$$

where B^i_{jA} are the five-vector gauge fields that correspond to the basis fields \vec{e}_i . From the latter formula it follows that in any regular five-vector basis

$$F^i_{j\alpha\beta} = F^{(\nabla)i}_{j\alpha\beta},$$

which is a reflection of the fact that the 2-form \mathbf{F}^∇ equals the $\tilde{\mathcal{Z}}$ -component of \mathbf{F} .

Each five-vector field strength tensor has an important differential property, which directly follows from its definition:

$$\mathbf{d}\mathbf{F} = \mathbf{0}, \quad (53)$$

where \mathbf{F} is regarded as a 2-form whose values are nonspacetime tensors of rank (1, 1). There are several

equivalent ways of proving equation (53). For example, one can present the field produced by the action of \mathbf{F} on an arbitrary 0-form \vec{s} as $\prec \mathbf{F} \wedge \vec{s} \succ$, where it is assumed that the value of \vec{s} is contracted with the value of \mathbf{F} as with a tensor, and then consider the quantity $\mathbf{d}\mathbf{d}\vec{s}$ and evaluate it in two different ways. On the one hand, $\mathbf{d}\mathbf{d}\vec{s} = \mathbf{d}(\mathbf{d}\vec{s})$, and since the action of \mathbf{d} is independent of the rank of the form, and the values of $\mathbf{d}\vec{s}$ and \vec{s} are elements of the same vector space, one has

$$\mathbf{d}\mathbf{d}\vec{s} = \prec \mathbf{F} \wedge \mathbf{d}\vec{s} \succ. \quad (54)$$

On the other hand, $\mathbf{d}\mathbf{d}\vec{s} = \mathbf{d}(\mathbf{d}\vec{s}) = \mathbf{d}\prec \mathbf{F} \wedge \vec{s} \succ$, and by using formula (43) one obtains

$$\mathbf{d}\mathbf{d}\vec{s} = \prec \mathbf{d}\mathbf{F} \wedge \vec{s} \succ + \prec \mathbf{F} \wedge \mathbf{d}\vec{s} \succ. \quad (55)$$

Comparing expressions (54) and (55) and considering that \vec{s} is an arbitrary 0-form, one concludes that the derivative $\mathbf{d}\mathbf{F}$ should be identically zero.

Equation (53) can also be proved by using definition (48) and the Jacobi identity in application to the commutators of operators \square , or by straightforward calculation with components. Since for any form $\tilde{\mathbf{t}}$ one has $(\mathbf{d}\tilde{\mathbf{t}})^{\tilde{\mathcal{Z}}} = \mathbf{d}^{\nabla}\tilde{\mathbf{t}}^{\tilde{\mathcal{Z}}}$, from equation (53) follows a similar differential identity for \mathbf{F}^{∇} :

$$\mathbf{d}^{\nabla}\mathbf{F}^{\nabla} = \mathbf{0},$$

which, naturally, can be proved in an independent way.

F. Nonspacetime analogs of five-vectors

The nonspacetime vectors which we have talked about so far and which are used in physics, for example, for describing the internal symmetries of elementary particles, resemble ordinary tangent vectors in the sense that at each space-time point their vector space is endowed only with a nondegenerate inner product and has no other additional structure similar to the \mathcal{Z} - \mathcal{E} splitting in the space of five-vectors. In accordance with this, on the parallel transport of such vectors one imposes no other constraints except for the requirements that it be linear and conserve the mentioned inner product, so at an appropriate choice of the relevant gauge fields, any given vector at the initial point can be transported into any vector of the same length at the final point, if this does not contradict the condition of the transport continuity. One may now ask the following question: can there be defined such nonspacetime vectors that would resemble five-vectors?

Let us try to imagine what properties such vectors should have. It goes without saying that at each space-time point they should form a certain finite-dimensional vector space, W , the dimension of which in the general case it is convenient to denote as $n+1$. Accordingly, in the following such vectors themselves will be referred to as $(n+1)$ -vectors, and will be denoted with lower-case Roman-type letters with an arrow: \vec{u} , \vec{v} , \vec{w} , etc. It is also natural to assume that the space of $(n+1)$ -vectors is endowed with some nondegenerate inner product, which will be denoted as η . All this, however, applies to ordinary nonspacetime vectors as well. It seems reasonable to suppose that $(n+1)$ -vectors differ from the latter in that their space is “split” into two invariant subspaces, which will be denoted as $W^{\mathcal{Z}}$ and $W^{\mathcal{E}}$, the first one of dimension n , the other one-dimensional. The space W itself will be the direct sum of these two subspaces, and the components of an arbitrary $(n+1)$ -vector \vec{u} in them will be denoted as $\vec{u}^{\mathcal{Z}}$ and $\vec{u}^{\mathcal{E}}$, respectively.

Since as in the case of ordinary nonspacetime vectors, it is not supposed that $(n+1)$ -vectors are associated with any manifold, the mentioned splitting will have a real meaning only if it manifests itself in some specific properties, basing on which one would be able to say that one is dealing with $(n+1)$ -vectors and not with some type of ordinary nonspacetime vectors of dimension $n+1$. It is apparent that if the space of $(n+1)$ -vectors is not endowed with any additional structure, then the above specific properties can only be related to parallel transport. Basing on the analogy with five-vectors, let us assume that $(n+1)$ -vectors from $W^{\mathcal{E}}$ are transported into $(n+1)$ -vectors from $W^{\mathcal{E}}$ and that $(n+1)$ -vectors from $W^{\mathcal{Z}}$ may acquire in the process of transport a nonzero \mathcal{E} -component. The first of these properties tells us that we are not dealing with ordinary nonspacetime vectors. The second property tells us that neither we are dealing with elements of the direct sum of two spaces of ordinary nonspacetime vectors (of dimension n and one). In addition to this, let us assume that parallel transport conserves the inner product

$$\theta(\vec{u}, \vec{v}) \equiv \eta(\vec{u}^{\mathcal{Z}}, \vec{v}^{\mathcal{Z}}),$$

which is the analog of the inner product g for five-vectors.

In order to write down the indicated properties of $(n+1)$ -vectors in the form of equations, let us introduce the following notations. The set of all sufficiently smooth fields whose values are $(n+1)$ -vectors of the considered type will be denoted as \mathbf{W} . An arbitrary set of basis fields from \mathbf{W} will be denoted as $\vec{e}_1, \dots, \vec{e}_{n+1}$. In those cases where it cannot lead to confusion with similar notations for the analogs of five-

vectors in three-dimensional Euclidean space, it will be taken that lower-case latin indices run 1 through n , while capital Greek indices will be assumed to run 1 through $n + 1$. Often, instead of the value $n + 1$ I will use the symbol $\&$.

The basis in \mathcal{W} can be chosen arbitrarily. However, for practical reasons it is more convenient to select it in such a way that at each space-time point the $(n + 1)$ st basis vector belong to $W^\mathcal{E}$. Similarly to the case of five-vectors, such bases will be called *standard*. It is also useful to introduce the notion of a *regular* basis, whose first n elements belong to $W^\mathcal{Z}$ and the $(n + 1)$ st element is normalized in some particular way. Since $(n + 1)$ -vectors are not associated with any manifold, and therefore cannot be represented with differential-algebraic operators, and since, as one will see below, from the rules of their parallel transport one also cannot obtain any special normalization for the vectors from $W^\mathcal{E}$, the only condition that one can use for normalizing $\vec{e}_\&$ is the requirement $|\eta(\vec{e}_\&, \vec{e}_\&)| = 1$, which is similar to the normalization condition for the fifth basis vector in a normalized regular five-vector basis.

The connection coefficients for an arbitrary set of basis fields \vec{e}_Θ in \mathcal{W} are defined in the usual way:

$$\square_A \vec{e}_\Theta = \vec{e}_\Xi C_{\Theta A}^\Xi.$$

The quantities $C_{\Theta A}^\Xi$ will still be called *five-vector gauge fields*. From the assumptions made above about the parallel transport of $(n + 1)$ -vectors it follows that for any standard basis

$$C_{\& A}^i = 0, \quad (56)$$

which is the analog of constraint (20) on the connection coefficients for five-vector fields. Furthermore, if, for example, the considered $(n + 1)$ -vectors are complex and their inner product θ is Hermitian, there should hold the equation

$$\partial_A \theta_{ij} - \theta_{kj} (C_{iA}^k)^* - \theta_{ik} C_{jA}^k = 0, \quad (57)$$

similar to constraint (41) on the five-vector gauge fields associated with ordinary nonspacetime vectors.

From the assumptions made above it follows that parallel transport of $(n + 1)$ -vectors preserves the following equivalence relation on W :

$$\vec{u} \equiv \vec{v} \Leftrightarrow \vec{u} - \vec{v} \in W^\mathcal{E}.$$

It is a simple matter to check that with regard to their properties, the elements of the quotient space $W/W^\mathcal{E}$ are ordinary nonspacetime vectors, and that at each space-time point this quotient space, endowed with the inner product induced by the product θ on W , is

isomorphic to the subspace $W^\mathcal{Z}$. One should therefore expect that with each type of $(n + 1)$ -vectors there is associated a certain type of ordinary nonspacetime vectors, whose relation to the considered $(n + 1)$ -vectors is similar to the relation of four-vectors to five-vectors. For these associated vectors one can use all the notations and definitions that have been introduced earlier for ordinary nonspacetime vectors. In particular, if the gauge fields corresponding to them are defined by equation (39) and if the corresponding basis fields \vec{e}_i are such that at each point \vec{e}_i is the equivalence class of the basis $(n + 1)$ -vector \vec{e}_i , then by virtue of what has been said above there should hold the equation

$$C_{jA}^i = B_{jA}^i, \quad (58)$$

which is the analog of relation (48) of part II between the connection coefficients for four-vector and five-vector fields.

Let us now consider more closely the gauge fields $C_{\Theta A}^\Xi$. First of all, let us write down the formula for their transformation as one passes to another set of basis fields in \mathcal{W} :

$$C'_{\Xi A}^\Theta = (L^{-1})_\Delta^\Theta C_{\Sigma A}^\Delta L_{\Xi}^\Sigma + (L^{-1})_\Delta^\Theta \partial_A L_{\Xi}^\Delta, \quad (59)$$

where L_{Θ}^Ξ is the basis transformation matrix. If both bases are standard, one has $L_{\&}^i = (L^{-1})_{\&}^i = 0$, and at $\Theta = i$ and $\Xi = \&$ obtains

$$C'_{\& A}^i = (L^{-1})_k^i C_{lA}^k L_{\&}^l + (L^{-1})_k^i C_{\& A}^k L_{\&}^k + (L^{-1})_k^i \partial_A L_{\&}^k = 0,$$

which is actually a demonstration of the fact that from the validity of equation (56) in one standard basis follows its validity in any other such basis. In a similar manner, at $\Theta = i$ and $\Xi = j$ one has

$$C'_{jA}^i = (L^{-1})_k^i C_{lA}^k L_j^l + (L^{-1})_k^i \partial_A L_j^k,$$

so the connection coefficients C_{jA}^i transform as gauge fields corresponding to ordinary nonspacetime vectors, which agrees with equation (58).

Let us now turn to the gauge fields that determine the \mathcal{E} -components of the transported $(n + 1)$ -vectors. The first question one has to ask is whether parallel transport conserves the length of the vectors from $W^\mathcal{E}$. Since $(n + 1)$ -vectors are not associated with any manifold, the only measure available for the vectors from $W^\mathcal{E}$ is the scalar square constructed with the inner product η . As in the case of five-vectors, let us suppose that this scalar square does *not* change. In the case of real vectors this means that for any field of regular bases one should have $C_{\& A}^{\&} = 0$. In the case of complex vectors and Hermitian η , the fields

$C_{\&A}^{\&}$ for a regular basis do not have to vanish, and it is only necessary that they be imaginary. With transition to another basis in \mathcal{W} , but also a regular one, in the latter case one has $L_{\&}^{\&} = e^{i\alpha}$, so

$$\begin{aligned} C'_{\&A}{}^{\&} &= (L^{-1})_{\&}^{\&} C_{\&A}^{\&} L_{\&}^{\&} + (L^{-1})_{\&}^{\&} \partial_A L_{\&}^{\&} \\ &= C_{\&A}^{\&} + i \partial_A \alpha. \end{aligned}$$

There is one more constraint that can be imposed on the parallel transport of $(n+1)$ -vectors, which implicitly is very often imposed on the parallel transport of ordinary nonspacetime vectors. Namely, one can require that this transport conserve the Levi-Civita type tensor ϵ associated with the considered $(n+1)$ -vectors. In the case of real W this condition is equivalent to the conservation of the length of the $(n+1)$ -vectors from $W^{\mathcal{E}}$. In the case of complex W this requirement can be shown to imply that in any basis where the components of η and ϵ are constant, one should have $C_{\Theta A}^{\Theta} = 0$. What the latter equation results in will be seen below.

The gauge fields $C_{jA}^{\&}$ are evidently the analogs of the five-vector connection coefficients $H_{\mu A}^{\bar{5}}$. From formula (59) it follows that with transition to another basis in \mathcal{W} they transform as

$$\begin{aligned} C'_{jA}{}^{\&} &= (L^{-1})_{\Xi}^{\&} C_{lA}^{\Xi} L_j^l + (L^{-1})_{\&}^{\&} C_{\&A}^{\&} L_j^{\&} \\ &\quad + (L^{-1})_{\&}^{\&} \partial_A L_j^{\&} + (L^{-1})_{\&}^{\&} \partial_A L_j^{\&}. \end{aligned}$$

If both bases are regular, then $(L^{-1})_{\&}^{\&} = L_j^{\&} = 0$, and one has

$$C'_{jA}{}^{\&} = (L^{-1})_{\&}^{\&} C_{lA}^{\&} L_j^l. \quad (60)$$

If, in addition, one has $\vec{e}'_{\&} = \vec{e}_{\&}$, then simply

$$C'_{jA}{}^{\&} = C_{lA}^{\&} L_j^l.$$

An essential difference between the gauge fields $C_{jA}^{\&}$ and their five-vector counterparts is that for the former there does not exist a nonzero value that would be invariant under the transformations from the symmetry group of W . On the other hand, the value $C_{jA}^{\&} = 0$, which does not break this symmetry, has the unpleasant property that at it one cannot distinguish the considered $(n+1)$ -vectors from pairs made of an ordinary n -dimensional nonspacetime vector and a scalar. It is evident that at any nonzero $C_{jA}^{\&}$ the inner product η is not conserved by parallel transport, and since neither the requirement of the covariant constancy of θ nor a similar requirement for the n -plus-one-vector ϵ tensor impose any constraints on $C_{jA}^{\&}$, the latter can be absolutely arbitrary.

Let us examine in more detail the case of complex vectors for which the inner product η is Hermitian

and is positively definite. At each space-time point, let us select the basis in W orthonormal and such that one would have $\epsilon_{1\dots n\&} = 1$. Condition (57) will then acquire the form

$$\theta_{kj}(C_{iA}^k)^* + \theta_{ik} C_{jA}^k = 0,$$

whence it follows that the quantities $C_{ijA} \equiv \theta_{ik} C_{jA}^k$ are anti-Hermitian matrices with respect to the indices i and j . Since in the selected basis $C_{ijA} = C_{jA}^i$, one can write that

$$\begin{aligned} C_{jA}^i &= (i/2) g(t_a)^i_j C_A^a \\ &\quad + ig [2n(n+1)]^{-1/2} \delta_j^i C_A^0, \end{aligned} \quad (61)$$

where the index a runs 1 through n^2-1 ; the matrices $(t_a)^i_j$ are the usual (Hermitian) generators for the fundamental representation of $SU(n)$, normalized by the condition $\text{Tr}(t_a t_b) = 2\delta_{ab}$; the fields C_A^a and C_A^0 are real; and g is a dimensionless constant, which together with the factors $1/2$ and $[2n(n+1)]^{-1/2}$ is introduced for convenience. From the condition $C_{\Theta A}^{\Theta} = 0$ it follows that

$$C_{\&A}^{\&} = -ig [n/2(n+1)]^{1/2} C_A^0. \quad (62)$$

By using (61) and (62) one can write down the expression for the components of the five-vector covariant derivative of an arbitrary $(n+1)$ -vector field in the selected basis in the following way:

$$\begin{aligned} (\square_A \vec{u})^i &= \partial_A u^i + (i/2) g(t_a)^i_j C_A^a u^j \\ &\quad + ig [2n(n+1)]^{-1/2} C_A^0 u^i \end{aligned} \quad (63a)$$

$$\begin{aligned} (\square_A \vec{u})^{\&} &= \partial_A u^{\&} \\ &\quad - ig [n/2(n+1)]^{1/2} C_A^0 u^{\&} + g X_{jA} u^j, \end{aligned} \quad (63b)$$

where there has been introduced the notation $X_{jA} \equiv g^{-1} C_{jA}^{\&}$. Similarly, the expression for the components of the five-vector covariant derivative of a field \tilde{v} whose values are elements of the space \bar{W} of linear forms on W can be written down as follows:

$$\begin{aligned} (\square_A \tilde{v})_i &= \partial_A v_i - (i/2) g v_j (t_a)^j_i C_A^a \\ &\quad - ig [2n(n+1)]^{-1/2} v_i C_A^0 - g v_{\&} X_{iA} \end{aligned} \quad (64a)$$

$$(\square_A \tilde{v})_{\&} = \partial_A v_{\&} + ig [n/2(n+1)]^{1/2} v_{\&} C_A^0. \quad (64b)$$

If one disregards the terms involving the fields X_{iA} , the expressions obtained will have such a form as if one was dealing with the gauge fields corresponding to ordinary nonspacetime vectors and the gauge group was $SU(n) \times U(1)$. With respect to $SU(n)$ the sets of fields (u^1, \dots, u^n) and (v_1, \dots, v_n) transform according to the fundamental and anti-fundamental representations, respectively, and the fields $u^{\&}$ and $v_{\&}$ are singlets. With respect to the group $U(1)$ the

fields u^1, \dots, u^n all have the charge $g[2n(n+1)]^{-1/2}$, the field $u^\&$ has the charge $-g[n/2(n+1)]^{1/2}$, and the charges of the fields $v_1, \dots, v_\&$ are opposite to those of $u^1, \dots, u^\&$, which is in agreement with the fact that the field \tilde{v} can be obtained from some $(n+1)$ -vector field by conjugation (by the latter I mean the anti-linear map from W to \tilde{W} fixed by the inner product η , which is the analog of the map ϑ_h considered in section 3 of part II, and which in the selected basis coincides with ordinary Hermitian conjugation).

Besides C_A^a and C_A^o , the above expressions for the derivatives involve the gauge fields X_{jA} , due to which the covariant differentiation of the considered $(n+1)$ -vector fields in general does not commute with conjugation, as it can be clearly seen by comparing formulae (63) and (64). To gain a better understanding of what this noncommutativity implies, let us recall how one assigns a representation to matter fields in ordinary gauge theory when introducing new gauge fields. To be definite, let us consider the case where the gauge group in question is unitary. As always, the starting point is the existence of several matter fields in the theory, say, $\varphi^1, \dots, \varphi^n$, that enter the Lagrangian density in such a way that the latter is invariant under the replacement

$$\varphi^i \rightarrow \varphi'^i = L^i_j \varphi^j, \quad (65)$$

where L^i_j is an arbitrary constant unitary $n \times n$ matrix. One then gauges this symmetry by introducing the corresponding gauge fields, and as a result obtains the following expression for the derivative of the set $\varphi = (\varphi^1, \dots, \varphi^n)$:

$$(\nabla_\alpha \varphi)^i = \partial_\alpha \varphi^i + (i/2) g (t_a)_j^i B_\alpha^a \varphi^j + ig' B_\alpha^o \varphi^i,$$

where $(t_a)_j^i$ are the same as in formula (61), and for simplicity I omit the connection coefficients corresponding to other possible degrees of freedom of φ . By presenting the transformation formula for the considered matter fields in the form (65) one thereby states that this set of fields transforms according to the *fundamental* representation of the gauge group (= these fields are components of a corresponding nonspacetime *vector*). Equally well, one can label the fields with a *lower* index and, accordingly, write the rule for their transformation as

$$\varphi_i \rightarrow \varphi'_i = \varphi_j L^j_i.$$

By doing so one would state that the fields φ transform according to the *anti-fundamental* representation (= are components of a *linear form* associated with the relevant nonspacetime vectors), and the expression for the derivative would then acquire the

form

$$(\nabla_\alpha \varphi)_i = \partial_\alpha \varphi_i - (i/2) g \varphi_j (t_a)_i^j \tilde{B}_\alpha^a - ig' \varphi_i \tilde{B}_\alpha^o,$$

where $\varphi_i = \varphi^i$, $\tilde{B}_\alpha^o = -B_\alpha^o$, $\tilde{B}_\alpha^a = -\varepsilon_b^a B_\alpha^b$, and the coefficients ε_b^a are determined by the equation $(t_a)_j^i = (t_b)_i^j \varepsilon_b^a$. The transition from the fields $\varphi^i, B_\alpha^o, B_\alpha^a$ to the fields $\varphi_i, \tilde{B}_\alpha^o, \tilde{B}_\alpha^a$ and vice versa is a part of the charge conjugation operation.

By making similar transformations in formulae (63) and (64) one obtains

$$(\square_A \tilde{u})_i = \partial_A u_i - (i/2) g u_j (t_a)_i^j \tilde{C}_A^a - ig [2n(n+1)]^{-1/2} u_i \tilde{C}_A^o \quad (66a)$$

$$(\square_A \tilde{u})_\& = \partial_A u_\& + ig [n/2(n+1)]^{1/2} u_\& \tilde{C}_A^o + gu_j X_{jA}^j, \quad (66b)$$

and

$$(\square_A \tilde{v})^i = \partial_A v^i + (i/2) g (t_a)_j^i \tilde{C}_A^a v^j + ig [2n(n+1)]^{-1/2} \tilde{C}_A^o v^i - g X_{jA}^i v^\& \quad (67a)$$

$$(\square_A \tilde{v})^\& = \partial_A v^\& - ig [n/2(n+1)]^{1/2} \tilde{C}_A^o v^\&, \quad (67b)$$

where $u_\Theta = u^\Theta$, $v_\Theta = v^\Theta$, $X_{iA}^i = X_{iA}$, $\tilde{C}_A^o = -C_A^o$, $\tilde{C}_A^a = -\varepsilon_b^a C_A^b$, and the coefficients ε_b^a are the same as above. Comparing expressions (66) and (67) with expressions (64) and (63) respectively, we see that at $X_{iA} \neq 0$ they *do not coincide*. Consequently, the interaction with the fields X_{iA} is not C -invariant, and one should observe that in this case the charge asymmetry is implemented directly in the nonspacetime degrees of freedom of the fields.

The field strength tensor for the considered gauge fields can be defined in the standard way. In an arbitrary regular five-vector basis with zero commutator the components of this tensor are given by the following evident formula:

$$F_{\Xi AB}^\Theta = \partial_A C_{\Xi B}^\Theta - \partial_B C_{\Xi A}^\Theta + C_{\Omega A}^\Theta C_{\Xi B}^\Omega - C_{\Omega B}^\Theta C_{\Xi A}^\Omega.$$

At $\Theta = i$ and $\Xi = j$, with account of equations (56) and (58), one obtains

$$\begin{aligned} F_{jAB}^i &= \partial_A C_{jB}^i - \partial_B C_{jA}^i + C_{kA}^i C_{jB}^k - C_{kB}^i C_{jA}^k \\ &= \partial_A B_{jB}^i - \partial_B B_{jA}^i + B_{kA}^i B_{jB}^k - B_{kB}^i B_{jA}^k, \end{aligned}$$

so these components coincide with those of the field strength tensor for the gauge fields associated with the ordinary nonspacetime vectors that correspond to the considered $(n+1)$ -vectors. In a similar manner one finds that

$$\begin{aligned} F_{\&AB}^i &= \partial_A C_{\&B}^i + C_{kA}^i C_{\&B}^k \\ &+ C_{\&A}^i C_{\&B}^i - (A \leftrightarrow B) = 0 \end{aligned} \quad (68)$$

and

$$\begin{aligned}
F_{\&AB}^{\&} &= \partial_A C_{\&B}^{\&} - \partial_B C_{\&A}^{\&} + C_{\&A}^{\&} C_{\&B}^{\&} \\
&\quad - C_{\&B}^{\&} C_{\&A}^{\&} = \partial_A C_{\&B}^{\&} - \partial_B C_{\&A}^{\&}, \\
F_{jAB}^{\&} &= \partial_A C_{jB}^{\&} + C_{kA}^{\&} C_{jB}^k \\
&\quad + C_{\&A}^{\&} C_{jB}^{\&} - (A \leftrightarrow B).
\end{aligned}$$

In terms of the fields X_{jA} the latter formula can be rewritten as

$$\begin{aligned}
g^{-1} F_{jAB}^{\&} &= \partial_A X_{jB} - X_{kB} C_{jA}^k + C_{\&A}^{\&} X_{jB} - (A \leftrightarrow B) \\
&= \partial_A X_{jB} - (ig/2) X_{kB} (t_a)^k_j C_A^a \\
&\quad - (ig) [(n+1)/2n]^{1/2} C_A^0 X_{jB} - (A \leftrightarrow B)
\end{aligned}$$

or

$$F_{jAB}^{\&} = g (\mathbf{d}\tilde{\mathbf{X}})_{jAB}^{\&}, \quad (69)$$

where $\tilde{\mathbf{X}}$ is the five-vector 1-form with components $(\tilde{\mathbf{X}})_{jA}^{\&} = X_{jA}$, whose values are elements of the tensor product of the subspace $W^{\mathcal{E}}$ and the subspace $\tilde{W}^{\mathcal{Z}} \subset \tilde{W}$ of linear forms on W that have zero contraction with the $(n+1)$ -vectors from $W^{\mathcal{E}}$. All this is in agreement with the fact that with transition from one regular basis in \mathbf{W} to another the fields $C_{jA}^{\&}$ transform according to formula (60), i.e. according to the anti-fundamental representation with respect to $SU(n)$ and with the charge equal to the difference of the charges of $u^{\&}$ and u^i , with respect to $U(1)$. In a similar manner, in terms of the fields C_A^a and C_A^0 , the formulae for F_{jAB}^i and $F_{\&AB}^{\&}$ acquire the form

$$\begin{aligned}
F_{jAB}^i &= (ig/2) (t_a)^i_j F_{AB}^a \\
&\quad + (ig) [2n(n+1)]^{-1/2} \delta_j^i F_{AB}^0
\end{aligned} \quad (70)$$

$$F_{\&AB}^{\&} = (-ig) [n/2(n+1)]^{1/2} F_{AB}^0, \quad (71)$$

where

$$F_{AB}^a = \partial_A C_B^a - \partial_B C_A^a - g f_{bc}^a C_A^b C_B^c$$

and

$$F_{AB}^0 = \partial_A C_B^0 - \partial_B C_A^0,$$

and the structure constants f_{bc}^a are defined as follows: $[t_a, t_b] = 2i t_c f_{ab}^c$.

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